## Introduction to Programming LEGO® MINDSTORM® EV3



## **Data Logging: Interpretation**

Answer the following questions based on the data you have collected, and the analysis you have conducted.

- 1. There should be two lines on your graph. What does each represent?
- 2. The Data Logging Block was set to record 40 points of data each second during the experiment. What happened to those data points?
  - Hint: Click the "Color and Plot Style" button next to one of the lines on your Dataset Table. Choose one of the shapes for "Plot Style".
- 3. Our original hypothesis was that the Gyro Sensor "lagged" behind the actual robot's body when turning
  - Compare the times at which the two sensors said the robot reached the 200-degree mark.
    - 1. How do the two values compare? Which one comes earlier, and which one comes later?
    - 2. What does this suggest about the behavior of the Gyro Sensor?
    - 3. Does this support or refute the hypothesis?
  - Compare the amount of turn the two sensors said the robot had made at 0.5 seconds into the program.
    - 1. How do the two values compare? Which one says the robot has turned farther, and which one says the robot has turned less?
    - 2. What does this suggest about the behavior of the Gyro Sensor?
    - 3. Does this support or refute the hypothesis?
  - Write a one-paragraph conclusion based on the analysis and interpretation you performed in the last few steps..
    - 1. State the original question being examined, along with the initial hypothesis.
    - 2. Explain the procedure you used to gather your data. Not every detail, just the parts that relate to answering the original question.
    - 3. State what the data showed.
    - 4. How do the two values compare? Which one says the robot has turned farther, and which one says the robot has turned less?
    - 5. State your conclusion about the answer to the original question.